

Elementary
Graph Algorithms

PART-1

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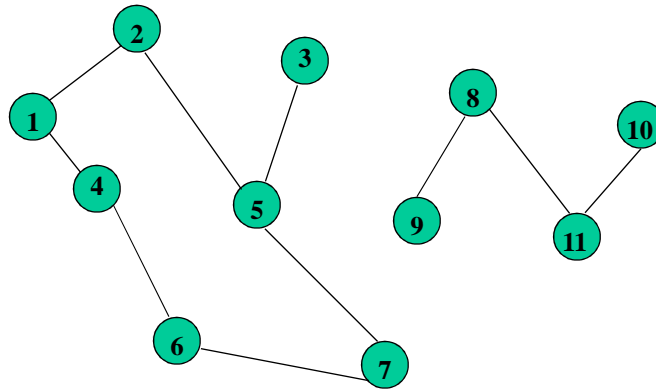
Outlines: Graphs Part-1

- Applications on Graphs
 - Communication Networks
 - Driving Distance /Time Map
 - Street Map
 - Computer Networks
- Graph Terminology
 - Undirected vs. Directed
 - Adjacent Vertices
 - Incident Edges
 - Path & Simple Path
 - Loops
 - Cycles & Simple Cycles
 - Weighted Graph
 - Complete Graph
 - Subgraph
 - Connected Graph & Component
 - Strongly vs. Weakly Connected
 - Symmetric Graph
 - Tree vs. Forest
 - End vertices (End points)
 - Parallel edges
 - Number of Edges
 - Sum of Vertex Degrees
 - In-degree and Out-degree
- Graph Representation
 - Adjacency Matrix
 - Adjacency Lists

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Applications: Communication Network

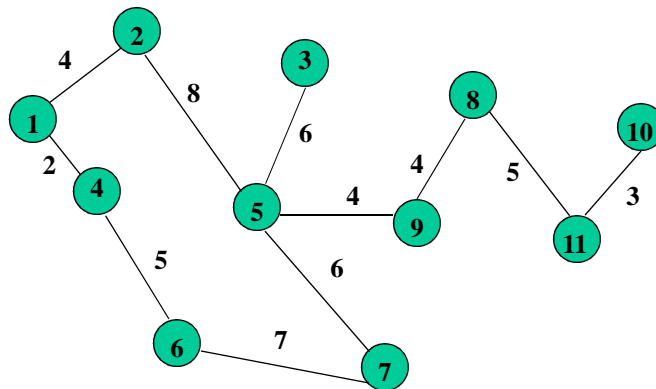
- *vertex* = city, *edge* = communication link



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Driving Distance/Time Map

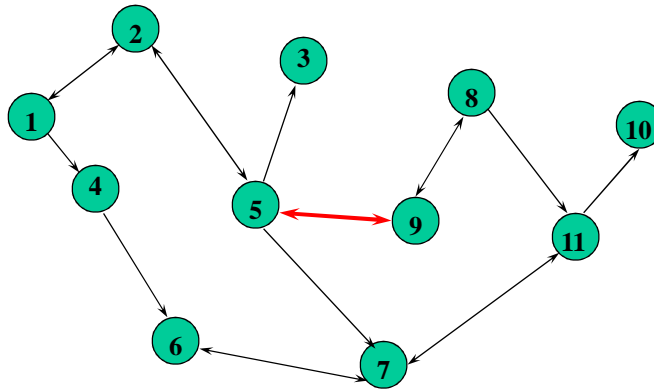
- *vertex* = city,
- *edge weight* = driving distance/time



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Street Map

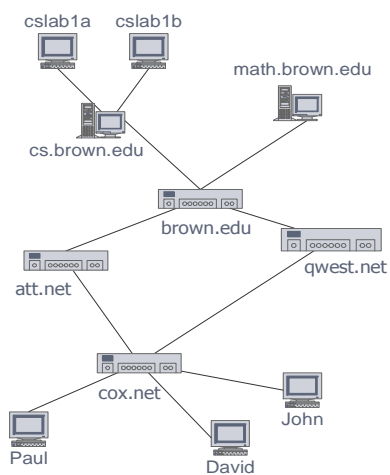
- Some streets are one way
- A *bidirectional* link represented by 2 directed edge
 - $(5, 9)$ $(9, 5)$



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Computer Networks

- Electronic Circuits
 - Printed Circuit Board
 - Integrated Circuits (ICs)
- Computer networks
 - Local Area Network (LAN)
 - Internet
 - Web



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Graph Terminology

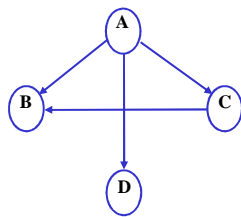
- A graph $G = (V, E)$
 - $V =$ set of vertices (nodes or points)
 - $E =$ set of edges (arcs or lines) = subset of $V \times V$
 - Thus $|E| \leq |V|^2 = O(|V|^2)$

- In an *undirected graph*:
 - $edge(u, v) = edge(v, u)$

- In a *directed graph*:
 - $edge(u, v)$ goes from vertex u to vertex v , notated $u \rightarrow v$
 - $edge(u, v)$ is **NOT** the same as $edge(v, u)$

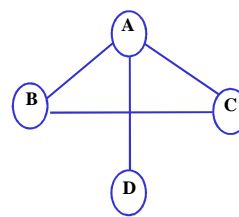
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Graph Terminology



Directed graph:

$V = \{A, B, C, D\}$
 $E = \{(A,B), (A,C), (A,D), (C,B)\}$



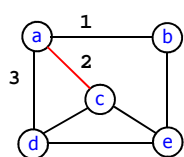
Undirected graph:

$V = \{A, B, C, D\}$
 $E = \{(A,B), (A,C), (A,D), (C,B), (B,A), (C,A), (D,A), (B,C)\}$

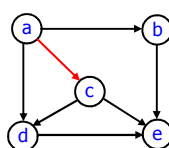
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Graph Terminology

- **Adjacent vertices:** connected by an edge
 - Vertex v is adjacent to u if and only if $(u, v) \in E$.
 - In an undirected graph with edge (u, v) , and hence (v, u) , v is adjacent to u and u is adjacent to v .
- **Incident edges:** on a vertex
 - For example, edges: 1, 2, and 3 are incident on vertex a .



Vertex a is adjacent to c and vertex c is adjacent to a

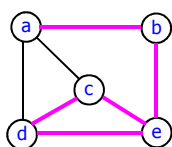


Vertex c is adjacent to a , but vertex a is NOT adjacent to c

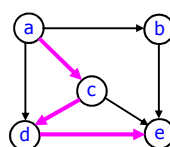
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Graph Terminology

- A **Path** in a graph from u to v is a **sequence of edges** between vertices w_0, w_1, \dots, w_k such that $(w_i, w_{i+1}) \in E$, $u = w_0$ and $v = w_k$, for $0 \leq i < k$
 - The **length of the path** is k , the number of edges on the path



abcede is a path.
cdeb is a path.
bca is NOT a path.



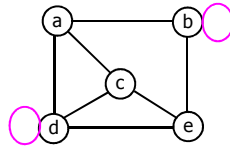
acde is a path.
abec is NOT a path.

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Graph Terminology

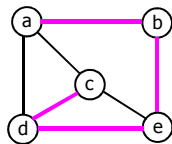
- **Loops**

- If the graph contains an edge (v, v) from a vertex to itself, then the path v, v is sometimes referred to as a *loop*.



- The graphs we will consider will generally be loopless.

- A *simple path* is a path such that *all vertices are distinct*, except that the first and last could be the same.

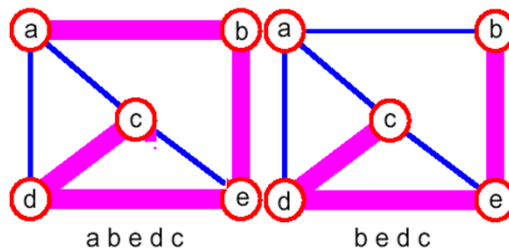


abedc is a simple path.
 cdec is a simple path.
 abedce is NOT a simple path.

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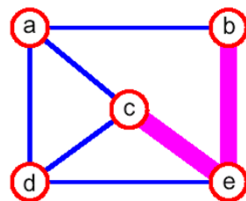
Graph Terminology

- **Simple path:** no repeated vertices



a b e d c

b e d c



b e c

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Graph Terminology

○ Path

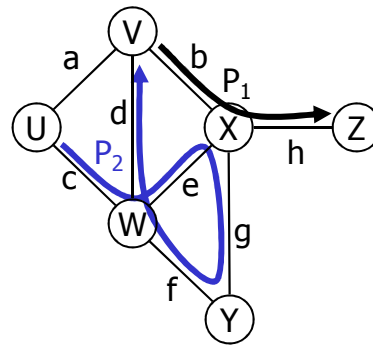
- sequence of alternating vertices and edges
- begins with a vertex
- ends with a vertex
- each edge is preceded and followed by its endpoints

○ Simple path

- path such that all its **vertices** and edges are **distinct**.

○ Examples

- $P_1 = (V, X, Z)$ is a simple path.
- $P_2 = (U, W, X, Y, W, V)$ is a path that is not simple.

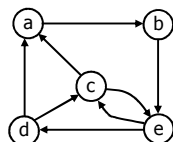


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Graph Terminology

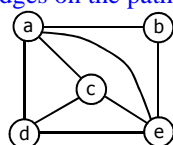
○ Cycles

- A **cycle** in a **directed graph** is a **path** of length at least 2 such that the **first** vertex on the path is the same as the **last** one; if the path is **simple**, then the cycle is a **simple cycle**.



abeda is a simple cycle.
abeceda is a cycle, but is NOT a simple cycle.
abedc is NOT a cycle.

- A **cycle** in an undirected graph
 - A path of length at least 3 such that the **first** vertex on the path is the same as the **last** one.
 - The edges on the path are **distinct**.

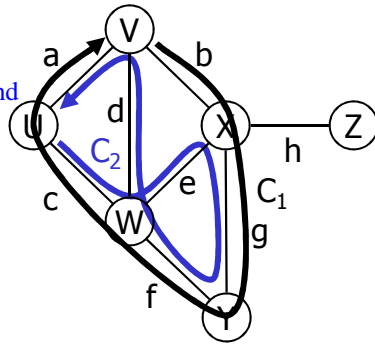


aba is NOT a cycle.
abedceda is NOT a cycle.
abedcea is a cycle, but NOT simple.
abea is a simple cycle.

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Graph Terminology

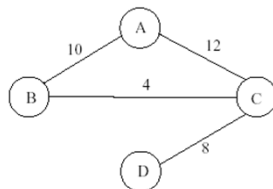
- **Cycle**
 - circular sequence of alternating vertices and edges
 - each edge is preceded and followed by its endpoints
- **Simple cycle**
 - cycle such that all its **vertices** and edges are **distinct**
- **Examples**
 - $C_1 = (V, X, Y, W, U, V)$ is a simple cycle
 - $C_2 = (U, W, X, Y, W, V, U)$ is a cycle that is not simple



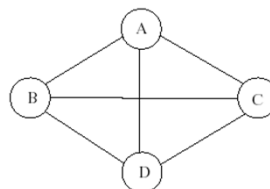
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Graph Terminology

- If each edge in the graph carries a value, then the graph is called **weighted graph**.
 - A weighted graph is a graph $G = (V, E, W)$, where each edge, $e \in E$ is assigned a real valued weight, $W(e)$.
- A **complete graph** is a graph with an edge between every pair of vertices.
 - A graph is called **complete graph** if every vertex is adjacent to every other vertex.



weighted graph

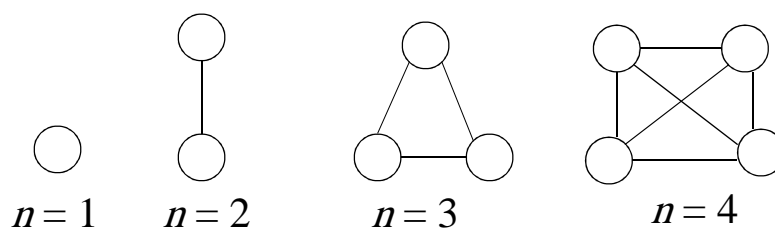


complete graph

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Graph Terminology

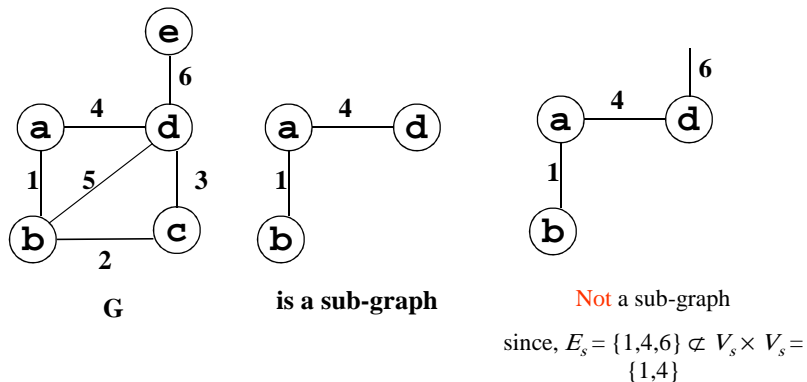
- Complete Undirected Graph
 - has all possible edges



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Graph Terminology

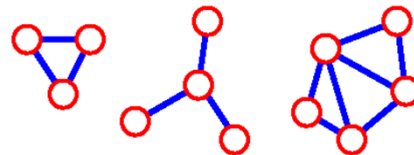
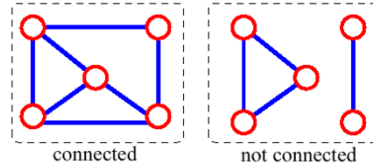
- **Subgraph:** subset of vertices and edges forming a graph
 - A graph $G_s = (V_s, E_s)$ is a *subgraph* of a graph $G = (V, E)$ if $V_s \subseteq V$, $E_s \subseteq E$, and $E_s \subseteq V_s \times V_s$.



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Graph Terminology

- **connected graph:** any two vertices are connected by some path
 - An undirected graph is *connected* if, for every pair of vertices u and v there is a path from u to v .
- **connected component:** maximal connected subgraph. E.g., the graph below has 3 connected components



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Graph Terminology

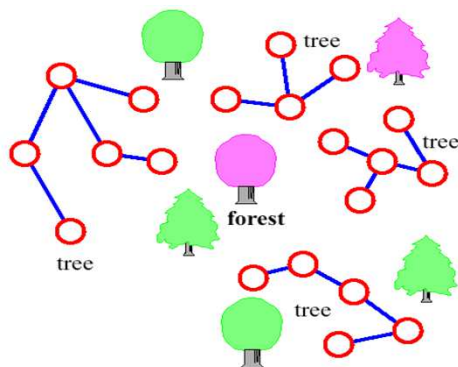
- A *directed graph* is *strongly connected* if every two vertices *are reachable from each other*.
 - Note that in a directed graph, the existence of a path from u to v does not imply there is a path from v to u .
- A directed graph that is *not strongly connected*, but the *underlying graph is connected*, is called *weakly connected*.
- A *symmetric digraph* is a directed graph, $G = (V, E)$, such that if $(u, v) \in E$, then $(v, u) \in E$.

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Graph Terminology

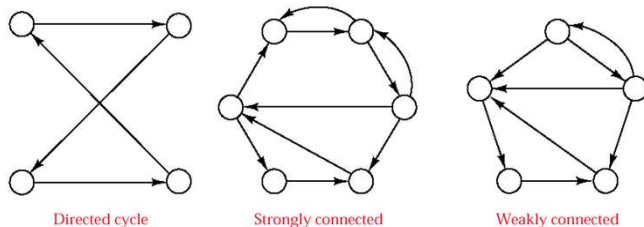
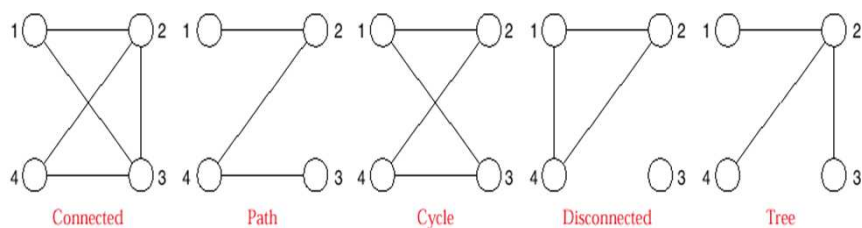
○ **tree** - connected undirected graph without cycles

○ **forest** - collection of trees



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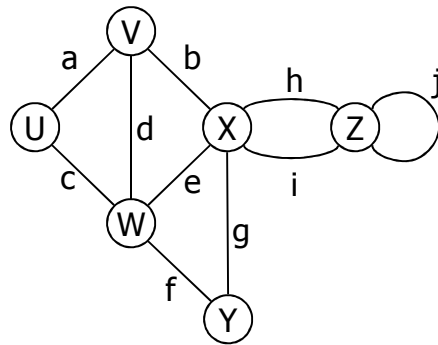
Graph Terminology



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Graph Terminology

- **End vertices** (or *endpoints*) of an *edge*
 - **U** and **V** are the endpoints of **a**
- **Edges incident** on a vertex
 - **a**, **d**, and **b** are incident on **V**
- **Adjacent vertices**
 - **U** and **V** are adjacent
- **Degree of a vertex**
 - **X** has degree 5
- **Parallel edges**
 - **h** and **i** are parallel edges
- **Self-loop**
 - **j** is a self-loop



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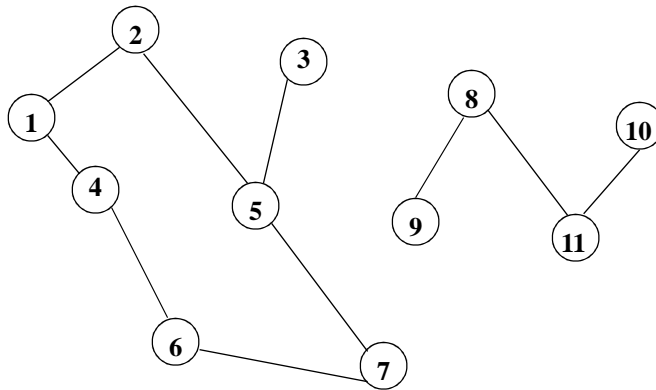
Number of Edges

- Each edge is of the form (u, v) , $u \neq v$
- Number of such pairs in an n vertex graph is $n(n-1)$
- **Undirected Graph**
 - Since $edge(u, v)$ is the same as $edge(v, u)$, the number of edges in a complete undirected graph is $n(n-1)/2$
 - Number of edges in an undirected graph is $\leq n(n-1)/2$
- **Directed Graph**
 - Since $edge(u, v)$ is not the same as $edge(v, u)$, the number of edges in a complete directed graph is $n(n-1)$
 - Number of edges in a directed graph is $\leq n(n-1)$

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Vertex Degree

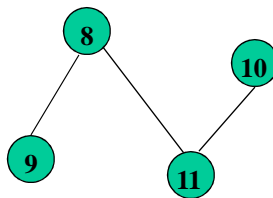
- **degree** (of a **vertex**): # of adjacent vertices
 - $\text{degree}(2) = 2, \text{degree}(5) = 3, \text{degree}(3) = 1$



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Sum of Vertex Degrees (undirected graph)

- Sum of degrees of all vertex = $2|E|$
 - Since adjacent vertices each count the adjoining edge, it will be counted twice

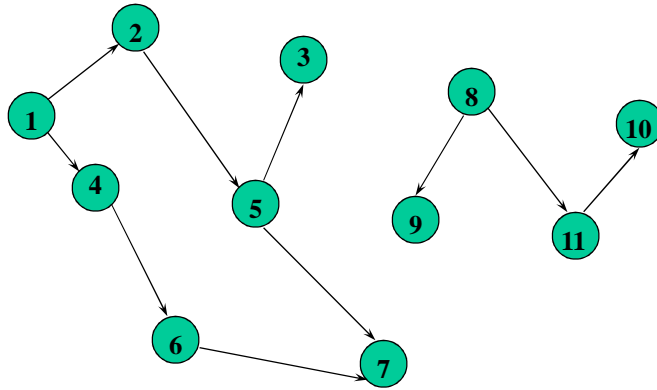


$$\sum_{v \in V} \text{deg}(v) = 2(\# \text{ of edges})$$

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In-Degree of a Vertex (digraph)

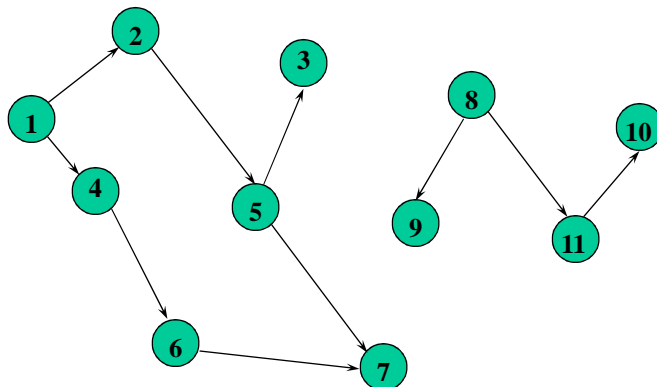
- **in-degree** is number of incoming edges
 - $\text{indegree}(2) = 1, \text{indegree}(8) = 0$



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Out-Degree of a Vertex (digraph)

- **out-degree** is number of outbound edges
 - $\text{outdegree}(2) = 1, \text{outdegree}(8) = 2$



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Sum of In- and Out-Degrees (digraph)

- Each edge contributes 1 to the **in-degree** of some vertex and 1 to the **out-degree** of some other vertex
- Sum of in-degrees = sum of out-degrees = $|E|$,
 - where $|E|$ is the number of edges in the digraph

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Graphs

- We will typically express running times in terms of
 - $|V|$ = number of vertices, and
 - $|E|$ = number of edges
 - If $|E| \approx |V|^2$ the graph is *dense*
 - If $|E| \approx |V|$ the graph is *sparse*
- If you know you are dealing with dense or sparse graphs, different data structures may make sense

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Graph Representation

- Adjacency Matrix
- Adjacency Lists

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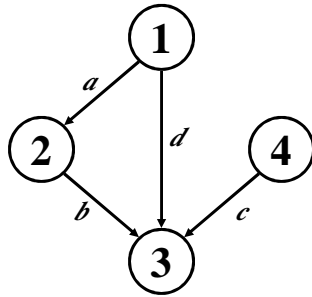
Adjacency Matrix

- Assume $V = \{1, 2, \dots, n\}$
- An *adjacency matrix* represents the graph as a $n \times n$ matrix A :
 - $A[i, j] = 1$ if $edge(i, j) \in E$ (or weight of edge)
 $= 0$ if $edge(i, j) \notin E$

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Adjacency Matrix

○ Example:

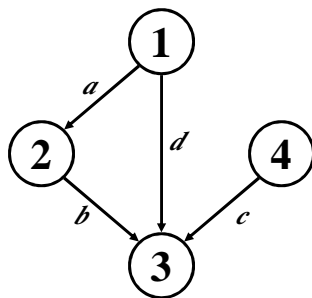


<i>A</i>	1	2	3	4
1				
2				
3			??	
4				

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Adjacency Matrix

○ Example:

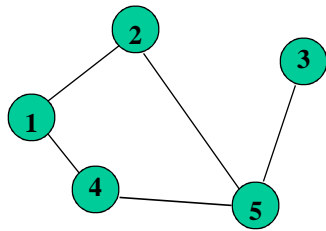


<i>A</i>	1	2	3	4
1	0	1	1	0
2	0	0	1	0
3	0	0	0	0
4	0	0	1	0

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Adjacency Matrix

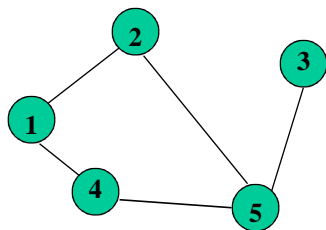
- $0/1$ $n \times n$ matrix, where $n = \#$ of vertices
- $A(i, j) = 1$ iff (i, j) is an edge



	1	2	3	4	5
1	0	1	0	1	0
2	1	0	0	0	1
3	0	0	0	0	1
4	1	0	0	0	1
5	0	1	1	1	0

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Adjacency Matrix

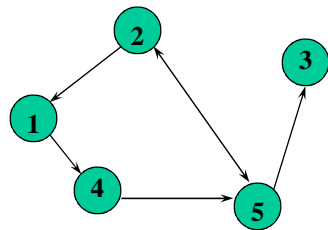


	1	2	3	4	5
1	0	1	0	1	0
2	1	0	0	0	1
3	0	0	0	0	1
4	1	0	0	0	1
5	0	1	1	1	0

- Diagonal entries are zero
- Adjacency matrix of an **undirected graph** is symmetric
 - $A(i, j) = A(j, i)$ for all i and j

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Adjacency Matrix



	1	2	3	4	5
1	0	0	0	1	0
2	1	0	0	0	1
3	0	0	0	0	0
4	0	0	0	0	1
5	0	1	1	0	0

- Diagonal entries are zero
- Adjacency matrix of a **digraph** need not be symmetric

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Adjacency Matrix

- How much *storage* does the adjacency matrix require?
 - Answer: $O(|V|^2)$
- $O(|V|)$ time to find vertex degree and/or *vertices adjacent* to a given vertex
- What is the *minimum amount of storage* needed by an adjacency matrix representation of an *undirected* graph with 4 vertices? $(|V|-1)|V|/2$
 - Answer: 6 bits
 - Undirected graph → matrix is symmetric
 - No self-loops → don't need diagonal

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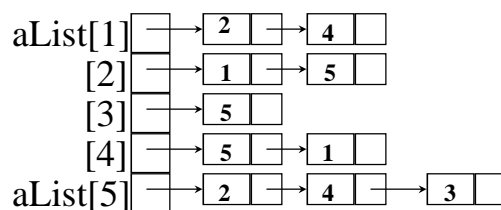
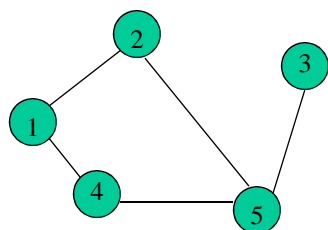
Adjacency Matrix

- The adjacency **matrix** is a **dense** representation
 - Usually too much storage for large graphs
 - But can be very efficient for **small** graphs
 - If graph is **unweighted**, there is an additional advantage in storage for the adjacency matrix presentation; rather than using one word of computer memory for each matrix entry, the adjacency matrix uses only one bit per entry.
 - Prefer to be a **directed** graph.
- Most large interesting graphs are **sparse**
 - For this reason the **adjacency list** is often a more appropriate representation

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Adjacency List

- Adjacency list: for each vertex $v \in V$, store a list of vertices adjacent to v .
- Adjacency list for vertex i is a **linear list** of vertices adjacent from vertex i
- Each adjacency list is a **chain**.

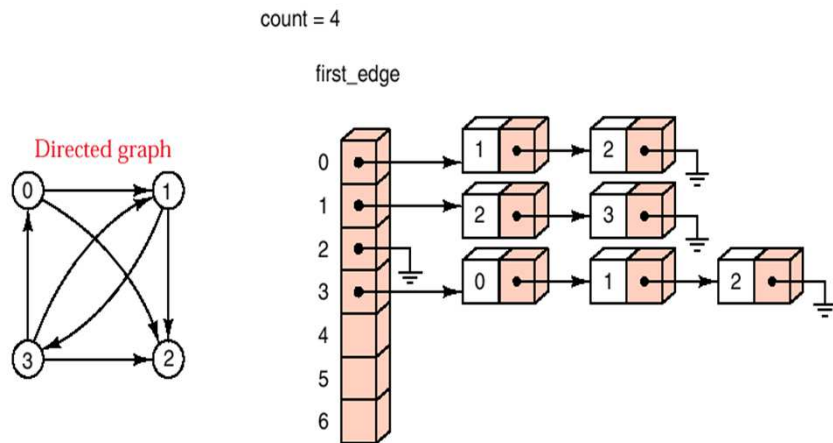


of chain nodes = $2|E|$ (undirected graph)

of chain nodes = $|E|$ (digraph)

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Adjacency List



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Adjacency List

- How much storage is required?
 - The *degree* of a vertex $v = \#$ incident edges
 - Directed graphs have in-degree and out-degree
 - For directed graphs:
 - # of items in adjacency lists is $\sum \text{out-degree}(v) = |E|$
 - takes $\Theta(V + E)$ storage (*Why?*)
 - For undirected graphs:
 - # items in adjacency lists is $\sum \text{degree}(v) = 2|E|$
 - also $\Theta(V + E)$ storage
- So: Adjacency lists take $\mathcal{O}(V + E)$ storage

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